





FIG 3

BEST AVAILABLE COPY

76

createSweep(uTextureID: GLuint, bcCenter: GLfboat, bCenter: GLfboat, bcCenter: GLfboat, bWidth: GLfboat, b/Length: GLfboat, bcHeight: GLfboat, bcHoat): void · RadarFrontEnd(pConfig: RadarCtg.pBackEnd: RadarBackEnd,cxWidth: GLint,cyHeight: GLint) : void RadarFrontEnd orthoMode(xLeft: GLInt,xRight: GLuint,yBottom: GLint,yTop: GLint) : void renderMotionBlur(uiTextureID: GLuim): void createTexture(ulTextureID: GLuim) : void ulpRenderTexture[65536][3]: GLuint pRadarBackEnd: *RadarBackEnd IpSweepTexture[128][4]: GLftoat · continueRendering() : void · updateParameters() : void renderHeloSymbol(): void perspectiveMode(): void -RadarFrontEnd(): void - pauseRendering() : void hpTextures(10) : GLuint pRadarCfg: *RadarCfg SweepIncrement: float bStopRendering: bool pFirstNtt: *CObjSpec renderScene() : void + getHeloYaw() : void LinearSize: GLuint SweepAngle: float MphaFade: float GainFactor: float bClearDisp : bool drawBlip(): void bStandby: bool cxCenter: float cyCenter: float bRotate : bool Range: float

F16.4

BEST AVAILABLE COPY

+ setHeloYOffset(rParam: UINT) : void + setHeloYPos(rParam: UINT) : void + setHeloXPos(rParam: UINT) : void

getModeSpeed(): UINT

+ getRcvrGain(): UINT

- getEraseGPI(): UINT

· getStab() : UINT

- getPersist(): UINT - getRange(): UINT - getHeloXPos(): UINT getHeloYPos(): UINT

~RadarCfg(): void

- setModeSpeed(rParam: UINT) : void

cvHeloOffset: UINT

iModeSpeed: UINT

iRcvrGain: UINT

iEraseGPI: UINT iPersist: UINT Range: UINT cxHelo: UINT cyHelo: UINT

iStab: UINT

- setRcvrGain(rParam: UINT) : void

- setEraseGPI(rParam: UINT) : void

setStab(rParam: UINT) : void

+ setRange(rParam: UINT): void

- setPersist(rParam: int) : void

 $\bar{\omega}$

FIG 4- BEST AVAILABLE COPY

		_ /	ATO KEYSET
			NHIB RECAL COTTS MASLE
G000 HELO	14 06 18		SENSS FLIZ FLIZ SHIP TACAD HORIZ FLIZ ADJ CORP CORR
		1	R.D.E. RPM RADAR PERST CNTF
	[8] [2]		TACT Each Dr FLP Flyth
			HOOK DEST HOOK RECTR PECTR VERFY SYND TONG HOOK HELO
		@	COURCI HIE 44
			The same St.
		0	FLY REF ON ENCR DECR TO MARK TOP RANGE RANGE
			1 NEXI TABLE
010	00 00 00	3 .	W4 5 6E TUNE PPT OFF
1	090/001		7 § 9 — CLEAR ALERT CUE
5 (1) · · · · · · · · · · · · · · · · · · ·	RASTER INC RIGHT CONT.	5	BACK O ENTER DATEM :
		-	FIX NEW COST TRACK PAGE TRACK TRACK CLASS POSIT
		ja K	CORER CURR MARK RANGE MIGHT FROM FROM CURSR CECL CLCL
			INSRT FLIR DEEP SCUTL SELL SONO EDIT
			SEND SEND LINA INIT REGUE SYMB POINT SYNC DATA
			INIO INIT GPS SELF LAMP COUTE HELO OPEN TEST TEST
		O,	این ا
		- 113	

F1G. 5